## CS 295A/395D:

Artificial Intelligence

## Elementary Game Theory

Prof. Emma Tosch
30 March 2022

## Agenda

Review decision theory
Elementary game theory

- Optimum vs. optimal solutions
- Strategies
- Vocabulary


## Logistics

- BB theory assignment out today
- Exam through game theory
- Temporal reasoning pushed to next unit
- Exam next Friday (April 8)
- Next unit: temporal reasoning and program synthesis
- Removed machine learning


Note: "decision tree" also refers to a classification algorithm in machine learning and is completely different from the type of decision tree we will talk about here.

## Recap: Decision Theory

We can express taking actions in a world with uncertainty via decision trees

Decisions trees are temporally-ordered nodes where each level corresponds to alternating:

- Decision nodes - state of the system; outgoing edges represent different actions
- Chance nodes - probability distributions over outcomes; outgoing edges represent reachable states with some probability
- Reward nodes - utility obtained from following the path


## Recap: Maximize expected utility



$$
E U\left[a \mid e_{1}, e_{2}, \ldots\right]=\sum_{s^{\prime}} P\left(S_{t+1}=s^{\prime} \mid a, e_{1}, e_{2}, \ldots\right) U\left(s^{\prime}\right)
$$

Best action is the action a that maximizes

$$
E U\left[a \mid e_{1}, e_{2}, \ldots\right]
$$

Sum of the utility of actions taken.

## Recap: Comparing actions



$$
E U\left[a \mid e_{1}, e_{2}, \ldots\right]=\sum_{s^{\prime}} P\left(S_{t+1}=s^{\prime} \mid a, e_{1}, e_{2}, \ldots\right) U\left(s^{\prime}\right)
$$

Probability mass function - over all sources of uncertainty associated with this action.

Utility function

- Basic actions: reward
- Actions with subsequent actions with uncertain outcomes: EU of those actions







$\mathrm{T}_{1}$ gives us no information

$$
\begin{aligned}
E U\left[C_{1} \mid T_{1}=+\right]= & P\left(C_{1}=+\mid T_{1}=+\right)\left(\operatorname{cost}\left(C_{1}\right)+\operatorname{cost}\left(T_{1}\right)\right) \\
& +P\left(C_{1}=-\mid T_{1}=+\right)\left(\operatorname{cost}\left(C_{1}\right)+\operatorname{repair}\left(C_{1}\right)+\operatorname{cost}\left(T_{1}\right)\right)
\end{aligned}
$$

$$
E U\left[C_{2} \mid T_{1}=+\right]
$$



$$
\begin{aligned}
E U\left[C_{1} \mid T_{1}=+\right]= & P\left(C_{1}=+\mid T_{1}=+\right)\left(\operatorname{cost}\left(C_{1}\right)+\operatorname{cost}\left(T_{1}\right)\right) \\
& +P\left(C_{1}=-\mid T_{1}=+\right)\left(\operatorname{cost}\left(C_{1}\right)+\operatorname{repair}\left(C_{1}\right)+\operatorname{cost}\left(T_{1}\right)\right)
\end{aligned}
$$



## Deterministically

 choose the car with higher expected utility given $\mathrm{T}_{1}=+$$$
E U\left[C_{2} \mid T_{1}=+\right]=P\left(C_{2}=+\right)\left(\operatorname{cost}\left(C_{2}\right)+\operatorname{cost}\left(T_{1}\right)\right)+P\left(C_{2}=-\right)\left(\operatorname{cost}\left(C_{2}\right)+\operatorname{repair}\left(C_{2}\right)+\operatorname{cost}\left(T_{1}\right)\right)
$$





$$
E U\left[T_{1}\right]=P\left(T_{1}=+\right) E U\left(C_{1} \mid T_{1}=+\right)+P\left(T_{1}=-\right) U\left(T_{1}=-\right)
$$

If we deterministically choose $\mathrm{C}_{1}$ when $\mathrm{T}_{1}=+, \ldots$


$$
E U\left[T_{1}\right]=P\left(T_{1}=+\right) E U\left(C_{1} \mid T_{1}=+\right)+P\left(T_{1}=-\right) U\left(T_{1}=-\right)
$$



$$
E U\left[T_{1}\right]=P\left(T_{1}=+\right) E U\left(C_{1} \mid T_{1}=+\right)+P\left(T_{1}=-\right) U\left(T_{1}=-\right)
$$



$$
\begin{aligned}
E U\left[T_{1}\right]=P\left(T_{1}=+\right) E U\left(C_{1} \mid T_{1}=+\right)+P\left(T_{1}=-\right) E U\left(C_{2} \mid T_{1}=\right. & -) \\
& \text { If we deterministically choose } \mathrm{C}_{2} \text { when } \mathrm{T}_{1}=-, \ldots
\end{aligned}
$$

## When uncertainty comes from another agent's actions

Car example: taking an action in one branch closes off possibilities in another

- Randomness comes from
- Epistemic uncertainty about effects of past actions (e.g., accuracy of test results)
- Epistemic uncertainty about future state (e.g., quality of car)

Consider the case when randomness comes from another agent's actions...

## Example: Prisoner's Dilemma

You (agent P) and an accomplice (agent Q) have been arrested for a crime...


But Q also knows all this and must make
the same choices...

## Example: Prisoner's Dilemma

You (agent P) and an accomplice (agent Q) have been arrested for a crime...


## Both parties know this

## Example: Prisoner's Dilemma

$P$ and $Q$ have been arrested for a crime and separated for in Utility function:
Collective cost? the choice of whether or not to confess and each action is as. You don't know how your accomplice will act. What do you do?

|  | P silent | Ptalks |
| :---: | :---: | :---: |
| $\stackrel{\rightharpoonup}{\stackrel{\rightharpoonup}{\omega}}$ | $(0,0)$ | $(-2,-5)$ |
| $\stackrel{\rightharpoonup}{\omega}$ |  |  |
| $\sigma$ | $(-5,-2)$ | $(-10,-10)$ |

Both parties know this matrix

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P silent

P talks
-7 Both choose silent if both are using the same utility function

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Collective cost?
the choice of whether or not to confess and each action is as. You don't know how your accomplice will act. What do you do?

P silent

Ptalks

$-7$

What if one uses a different utility function?

## Example: Prisoner's Dilemma

You and an accomplice have been arrested for a crime and
Utility function:
Individual Cost? interrogation. You have the choice of whether or not to confe associated with a cost. You don't know how your accomplice will do?

|  | P silent | P talks |
| :---: | :---: | :---: |
| $\stackrel{\text { H }}{\stackrel{\text { ¢ }}{\sim}}$ | $(0,0)$ | $(-2,-5)$ |
| $\stackrel{\sim}{\square}$ | $(-5,-2)$ | (-10, -10) |

Both parties know this matrix

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P talks

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-2-10

Both parties know this matrix

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Both parties know this matrix

## Example: Prisoner's Dilemma

You and an accomplice have been arrested for a crime and
Local reasoning, rather than global interrogation. You have the choice of whether or not to confe associated with a cost. You don't know how your accomplice will



Example: Prisoner's Dilemma
You and an accomplice have beer interrogation. You have You (P) talk for a crime and Local reasoning, rather than global associated with a cost.
do?
$\qquad$ Q talks
You (P) stay silent
 E

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|  | P silent | $\begin{aligned} & \text { P talks } \\ & (-2-5) \end{aligned}$ |  |
| :---: | :---: | :---: | :---: |
| $\stackrel{\text { H }}{\text { H }}$ | $(0,0)$ |  |  |
| $\stackrel{\sim}{\sim}$ | $(-5,-2)$ | (-10, | 10) |

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You and an accomplice have been arrested for a crime and s interrogation. You have the choice of whether or not to confess associated with a cost. You don't know how your accomplice will

Consider a different payoff matrix do?

|  | P silent | P talks |
| :---: | :---: | :---: |
|  | $(-2,-2)$ | (0, -15) |
| $\approx$ | $(-15,0)$ | $(-10,-10)$ |

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## Example: Prisoner's Dilemma

You and an accomplice have been arrested for a crime and s interrogation. You have the choice of whether or not to confess

Assume Q uses collective utility, but P uses individual utility... associated with a cost. You don't know how your accomplice will ¿ do?

P silent


$-10$

## Example: Prisoner's Dilemma

You and an accomplice have been arrested for a crime and se

What if Q knows P's utility function and decides to mimic? interrogation. You have the choice of whether or not to confess associated with a cost. You don't know how your accomplice will act. Whan un you do?


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| :---: | :---: | :---: |
| $\stackrel{ \pm}{\stackrel{\rightharpoonup}{ \pm}}$ | $(-2,-2)$ | (0, -15) |
| $\xrightarrow[0]{\text { \% }}$ | $(-15,0)$ | $(-10,-10)$ |

## Incentivize talking

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(0, -15)
$(-10,-10)$


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P silent P talks

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| :---: | :---: |
| $\begin{aligned} & \stackrel{\rightharpoonup}{\bar{v}} \\ & \stackrel{\rightharpoonup}{\bar{\omega}} \\ & 0 \end{aligned}$ | $(-2,-2)$ |
| $\frac{\stackrel{n}{\square}}{\stackrel{\rightharpoonup}{0}}$ | $(-15,0)$ |

P talks

$$
(0,-15)
$$

$$
(-10,-10)
$$

## Example: 2-finger Morra

Choose between 1 and 2 fingers. $P$ wins if sum is even. $Q$ wins if sum is odd. Loser pays the winner.

## 

P plays 1
$(+2,-2)$
$(-3,+3)$

P plays 2
$(-3,+3)$
$(+4,-4)$

## Example: 2-finger Morra

Choose between 1 and 2 fingers. $P$ wins if sum is even. $Q$ wins if sum is odd. Loser pays the winner.

## 

P plays 1
P plays 2
0
0

0
0

## Example: 2-finger Morra

Choose between 1 and 2 fingers. P wins if sum is even. $Q$ wins if sum is odd. Loser pays the winner.

## $n$ $n$ $\frac{n}{0}$ 0 0 $N$ $n$ $n$ 0

P plays 1
$+2$
-3

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## Example: 2-finger Morra

Choose between 1 and 2 fingers. $P$ wins if sum is even. $Q$ wins if pays the winner.

## 

P plays 2
$(+2,-2)$
$(-3,+3)$

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| :---: | :---: | :---: |
| $\stackrel{\rightharpoonup}{\stackrel{\rightharpoonup}{\omega}}$ | $(-4,-4)$ | $(0,-6)$ |
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No free ride for $\mathbf{Q}$

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| :---: | :---: | :---: |
|  | $(-4,-4)$ | $(0,-6)$ |
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## Vocabulary \& Concepts

- Always assume local decision making (all players maximizing individual utility)
- Zero sum - every entry in global collective payoff is 0
- Pure strategy - always pick the same action no matter what
- Mixed strategy - pick an action probabilistically
- Dominant strategy - one action is strictly better no matter what the other plays does

